



### **Basics of Synthetic Aperture Radar Remote Sensing**

Interferometric Synthetic Aperture Radar (InSAR) Training Course

**Economic Cooperation Organization (ECO)** 

Prepared by Dr. Tayebe Managhebi Iranian Space Research Institute

20-22 June, 2022

Tehran, Islamic Republic of Iran



#### Introduction



• Since the SAR resolution cell contains a large number of scatterers, the phase of pixels seems randomly distributed.



$$Ae^{i\phi} = \sum_{k=1}^{N} A_k e^{i\phi_k}$$



### Introduction



• If the scene is observed in 2 images, in which the scatterers remain unchanged in the resolution cell, the <u>phase difference</u> between pixels of the 2 images can be exploited.

> SAR Polarimetry

> SAR Interferometry

# **SAR Interferometry**

5.7









 $S_1$  and  $S_2$  are the received signals at two satellite positions:

$$S_{1} = A_{1}e^{-j\varphi_{1}} = A_{1}e^{-j\frac{4\pi}{\lambda}r_{1}}$$

$$S_{2} = A_{2}e^{-j\varphi_{2}} = A_{2}e^{-j\frac{4\pi}{\lambda}r_{2}}$$

The interferogram is the map of the pixel-to-pixel phase differences between S1 and S2:

$$S_1 S_2^* = A_1 A_2 e^{-j\frac{4\pi}{\lambda}(r_1 - r_2)}$$







Interferogram: the image of the pixel to pixel phase differences.

An interferogram is a complex image with (a) <u>magnitude</u> given by the product of the SAR amplitudes and (b) <u>phase</u> (the InSAR phase) given by the path length difference, as well as variations of the scattering properties and the medium conditions.

Images must differ in at least one aspect (= "baseline")

- Temporal baseline
- Spatial baseline





#### Interferogram





ERS-1, Vesuvius, Italy







Single pass or simultaneous baseline: Two radars acquire data from different vantage points at the same time.



Repeat pass or repeat track: Two radars acquire data from different vantage points at different times.







## Image of an earthquake

Sniffing out transcription factors Tropical cradie for biodivorsity Seismological detection of a mantle plume?





#### If:

Then:

Earth was flat. The satellite orbit was fixed. No atmosphere.



Things were simple, and the calculation of ground deformation would have been indeed an easy task.



#### The interferometric phase contains some distinct contributions:



 $\varphi_{\text{int}} = \varphi_f + \varphi_{topo} + \varphi_{displ} + \varphi_{atm} + \varphi_{err}$ 



#### Displacement estimation











### **InSAR processing: Flat-earth removal**



Next, we need to remove the phase interferogram that would result from a flat-earth.  $\varphi_{int}$   $\varphi_f$ 



Removing the phase component due to the smooth Earth yields a "flattened interferogram"



### InSAR processing: Flat-earth removal





After removing the flat-earth effect we are left with an interferogram that contains **topography+deformation** between the two acquisitions and atmospheric effect.





$$\varphi_{\text{int}} = \varphi_{f} + \varphi_{topo} + \varphi_{displ} + \varphi_{atm} + \varphi_{err}$$

The altitude contribution can be subtracted from the interferometric phase (generating the so-called <u>differential</u> <u>interferogram</u>) and the terrain motion component can be measured.





The topographic phase can be removed by one of the following methods:

- $\odot$  Two-pass: Simulate  $\phi_{topo}$  based on existing DEM. High accuracy of DEM required.
- Three-pass: Derive  $\phi_{topo}$  from independent interferogram, no existing DEM is required.

Differential Interferometry (DInSAR)







Interferogram









The longer the baseline, the smaller the topographic height needed to produce a fringe of phase change (or, the longer the baseline is the stronger the topographic imprint).







The higher the baseline the more accurate the altitude measurement.

There is an upper limit to the perpendicular baseline, over which the interferometric signals decorrelate and no fringes can be generated





### In c-band the <u>fringes are closer</u> to each other than in L-band



Suppose that some of the point scatterers on the ground slightly change their relative position in the time interval between two SAR observations (as, for example, in the event of subsidence, landslide, earthquake, etc.). In such cases the following additive phase term, independent of the baseline, appears in the interferometric phase:  $\Delta \phi = \frac{4\pi}{4\pi} d$ 

where d is the relative scatterer displacement projected on the slant range direction.

This means that <u>after interferogram flattening</u>, the interferometric phase contains <u>both altitude and motion contributions</u>:

$$\Delta \phi = -\frac{4\pi}{\lambda} \frac{B_n q}{R \sin \theta} + \frac{4\pi}{\lambda} d$$



 $\Delta \phi_{d} = \frac{4\pi}{\lambda} d$ 





- If a DEM is available, the altitude contribution can be subtracted from the interferometric phase (generating the so-called differential interferogram) and the terrain motion component can be measured.
- In the ERS case with  $\lambda = 5.6$  cm and assuming a perpendicular <u>baseline of</u> <u>150 m (a rather common value)</u>, the following expression holds:

$$\Delta\phi = -\frac{q}{10} + 225 d$$

• From this example it can be seen that the sensitivity of SAR interferometry to terrain motion is much larger than that to the altitude difference.

A 2.8 cm motion component in the slant range direction would generate a  $2\pi$  interferometric phase variation.



The **altitude of ambiguity** guide us how the topography affect the interferometric phase.

The altitude of ambiguity  $h_a$  is defined as the <u>altitude difference that</u> <u>generates an **InSAR phase change** of  $2\pi$  after interferogram flattening.</u> The altitude of ambiguity is inversely proportional to the perpendicular baseline:

$$h_a = \frac{\lambda R \sin \theta}{2B_n}$$

For the case of ERS:  $\lambda = 5.6 \text{ cm}, \theta = 23^{\circ}$  and R=850 km

$$h_a \approx \frac{9300}{B_n}$$







Differential Interferometry (DInSAR)





H Coplans parties

CHT N

### **InSAR processing: Atmospheric phase**









### InSAR processing: Atmospheric phase



#### What is Atmospheric delay ?



Atmospheric delays include:

Ionospheric delayTropospheric delay

- Temperature and pressure
- Wet delay (water vapor instability)



#### InSAR processing: unwrapping



The interferogram is a map of an <u>ambiguous phase offset between</u> - $\pi$  and + $\pi$ . In order to recover the absolute unambiguous phase offset, one needs to <u>unwrap</u> the data.





#### InSAR processing: unwrapping



Phase unwrapping is the reverse-finding the integer shift values for each point.



#### **InSAR processing:** unwrapping

#### While the wrapped phase looks like this:

#### The unwrapped phase looks like this:

\* Note that in this specific example the topographic effect has not been removed, thus the unwrapped phase map correspond mainly to topographic height.









#### **Decorrelation**



• **Temporal decorrelation**: makes InSAR measurements unfeasible over <u>vegetated areas</u> and where the electromagnetic profiles and/or the positions of the scatterers change with time within the resolution cell.

• Geometrical decorrelation: limits the number of image pairs suitable for interferometric applications and prevents one from fully exploiting the data set available.



#### **Coherence Maps**







#### Coherence

interferogram



Azimuth [pix]



Phase Interf: 20160902-20151213, Bn: -110, Hamb: -148.1



Azimuth [pix]

800 Coher

Azimuth [pix]

800 Coher. 



#### **Time Series InSAR**



#### **Motivation!**

- Allows better selection of coherent pixels (in high temporally/ geometrically decorrelated areas)
- Atmosphere errors can be reduced by filtering in space and time
- DEM error estimation possible
- More reliable phase unwrapping possible (3-D)

Overcoming the limitations of D-InSAR





The Monitoring platform is currently capable of providing autonomous Multi-temporal InSAR (MT-InSAR) processing and generation of regularly updated displacement maps to find the risk area in the case of the collapse in Tehran.











- C-band
- Revisit time, 6/12 days
- Dual polarization in Iran
- Spatial resolution in IW mode: 20(Azimuth)×5(range) meters
  - <u>https://scihub.copernicus.eu/dhus/#/home</u>
  - <u>http://step.esa.int/main/download/snap-download/</u>





مانان نتغرداری تور

**Track 35 over Tehran** 





System Architecture













**System Architecture** 











## User Interface Application





**System Architecture** 







Time series of the selected point compared to its neighbor points.  $^{60}_{\phantom{0}\mathrm{F}}$ 





 InSAR is a powerful, low-cost tool for monitoring Earth deformation Capability improving continuously (smaller rates, bigger areas...) Future missions and method development will ensure InSAR is a standard technique